

Gravitational Lensing of Galaxies with a Hierarchical Dirichlet Process Prior

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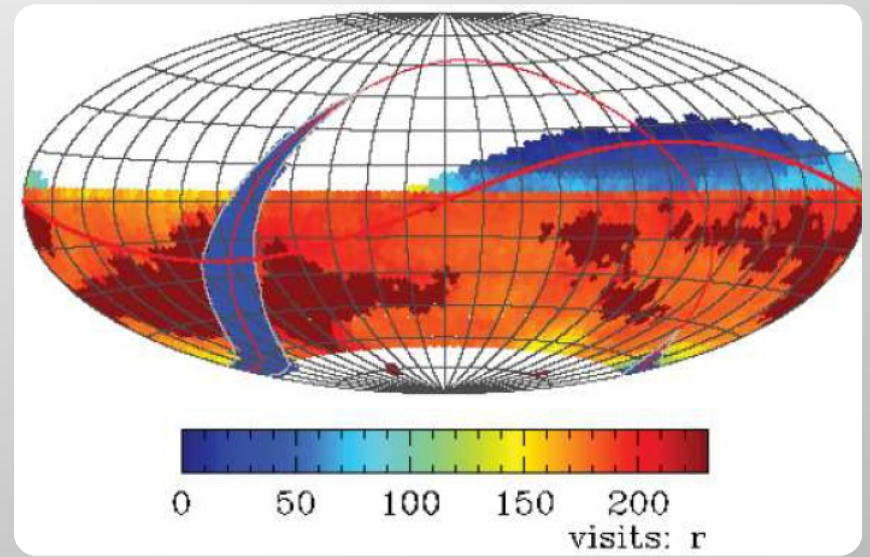
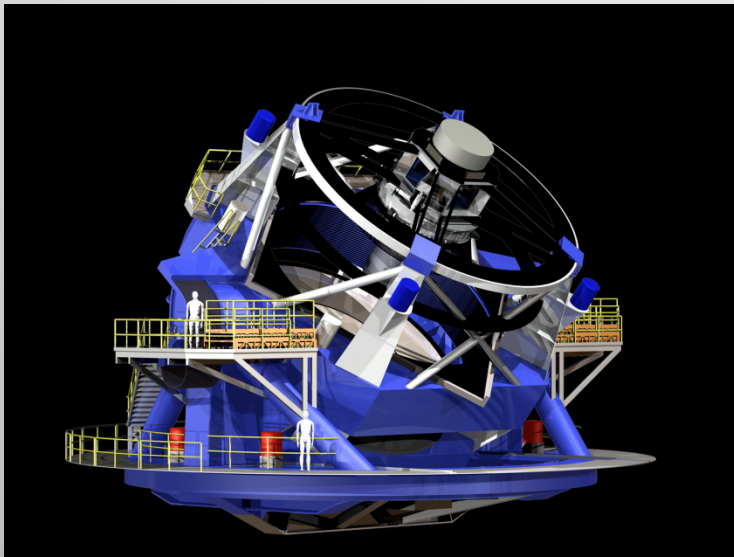
This work was performed under the auspices of the U.S. Department of Energy by Lawrence Livermore National Laboratory under Contract DE-AC52-07NA27344. Lawrence Livermore National Security, LLC



Large Synoptic Survey Telescope: A Deep, Wide, Fast, Uniform Sky Survey

Construction start: next month! First light: 2020

8.4m telescope 18,000+ deg² 10mas astrom. $r < 24.5$ (< 27.5 @ 10yr)
ugrizy 0.5-1% photometry



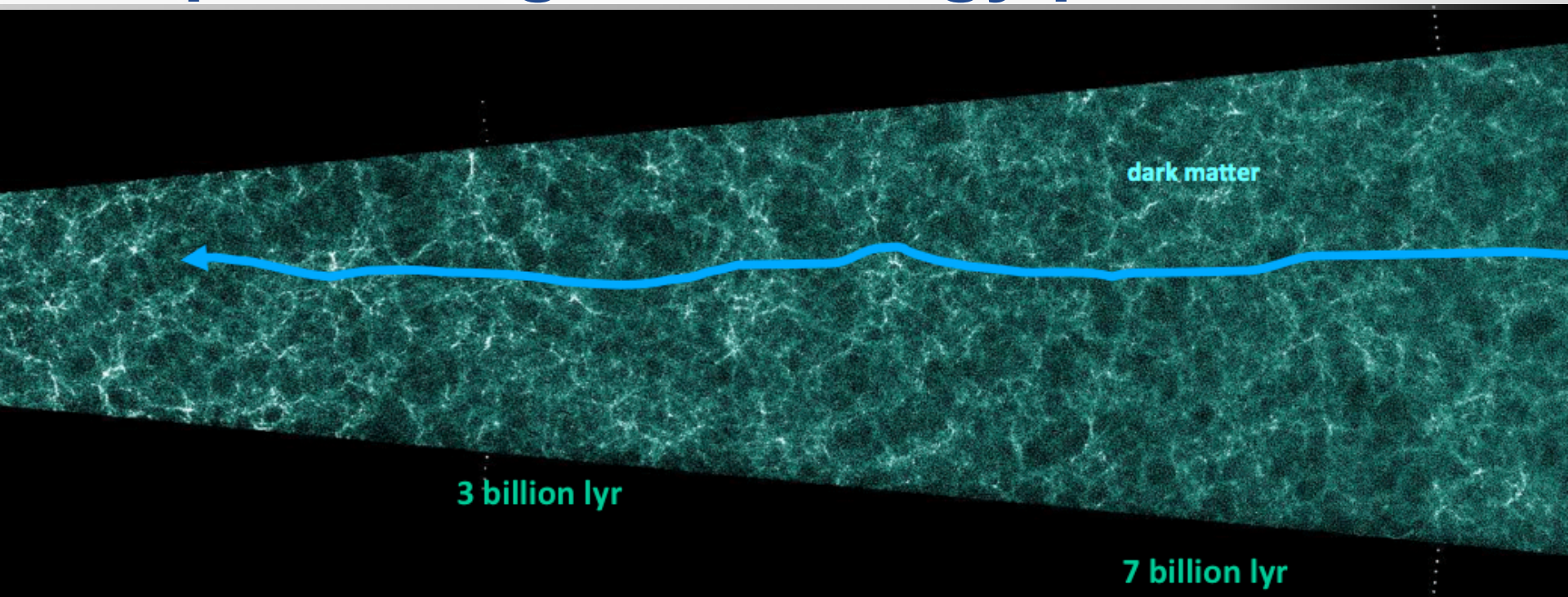
3.2Gpix camera 2x15sec exp/2sec read **15TB/night** **20 B objects**

Imaging the visible sky, once every 3 days, for 10 years (825 revisits)

Credit: T. Tyson

Gravitational lensing traces mass structure vs cosmic time

- promising dark energy probe



LSST will give positions, shapes, and distance estimates of 4 billion galaxies.

But to measure gravitational lensing, we need to measure galaxy shapes...

- Lensing is a small distortion ($<1\%$)
- Distortions due to atmosphere, telescope, CCD, measurement method are large ($>\sim 10\%$)!



Galaxies: Intrinsic galaxy shapes to measured image:

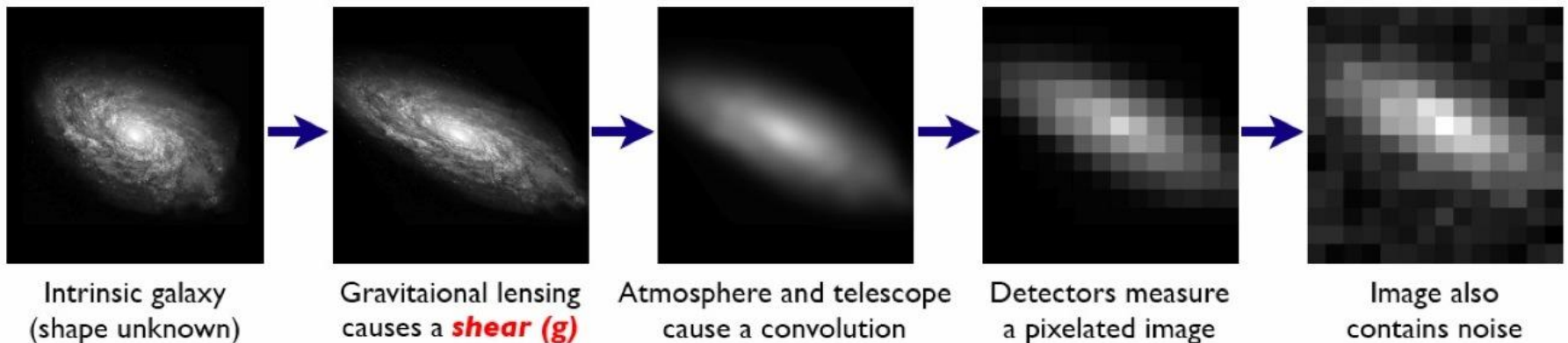
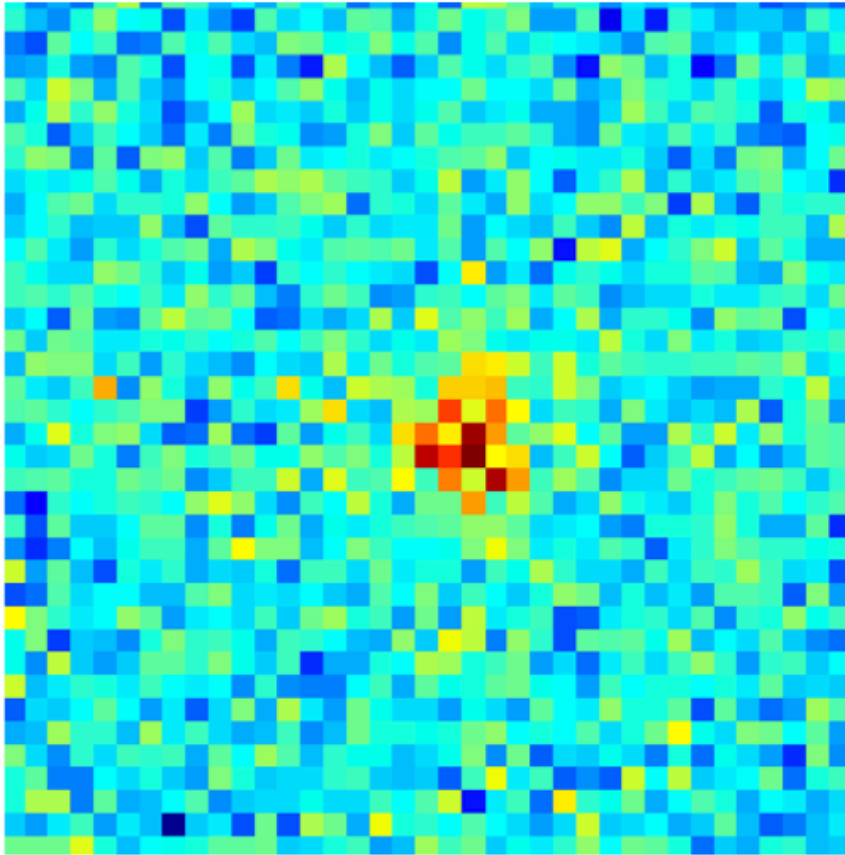


Image credit: S. Bridle

A typical galaxy image for cosmic shear



Intrinsic galaxy shape
 $b/a \sim 0.5$

Uncertainty due to noise
 $\sigma b/a \sim 0.5$

Modification due to lensing
 $\Delta b/a \sim 0.05$

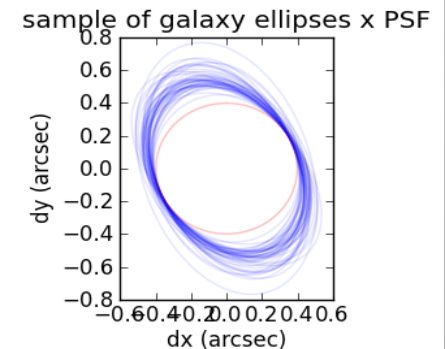
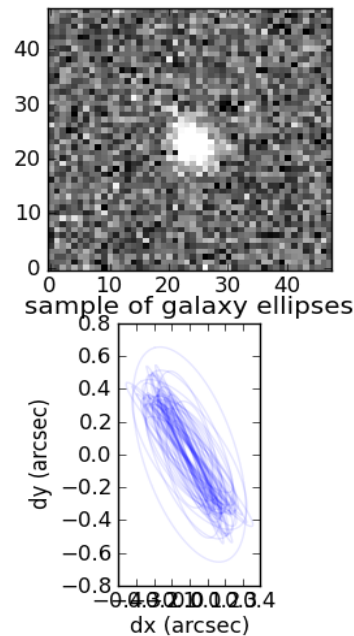
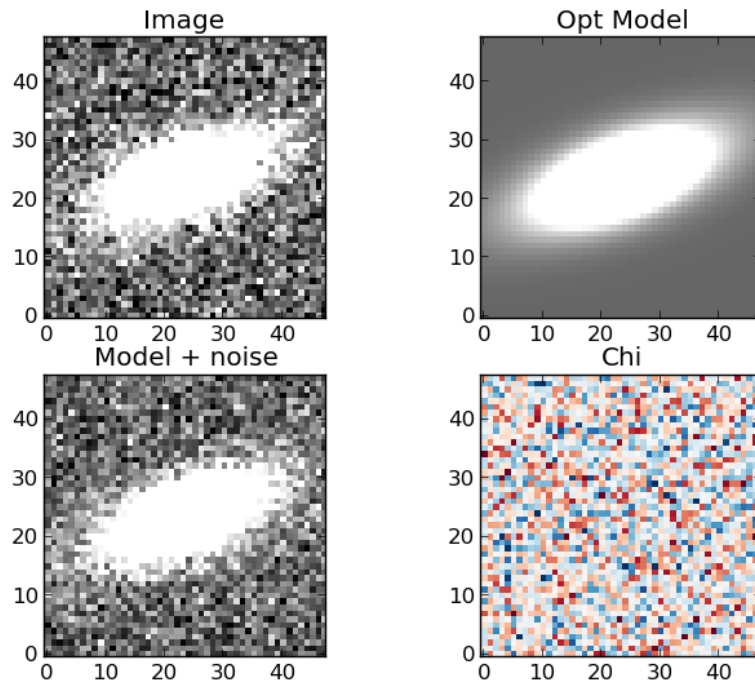
Effect of changing w by 1%
 $\delta b/a \sim 0.0005$



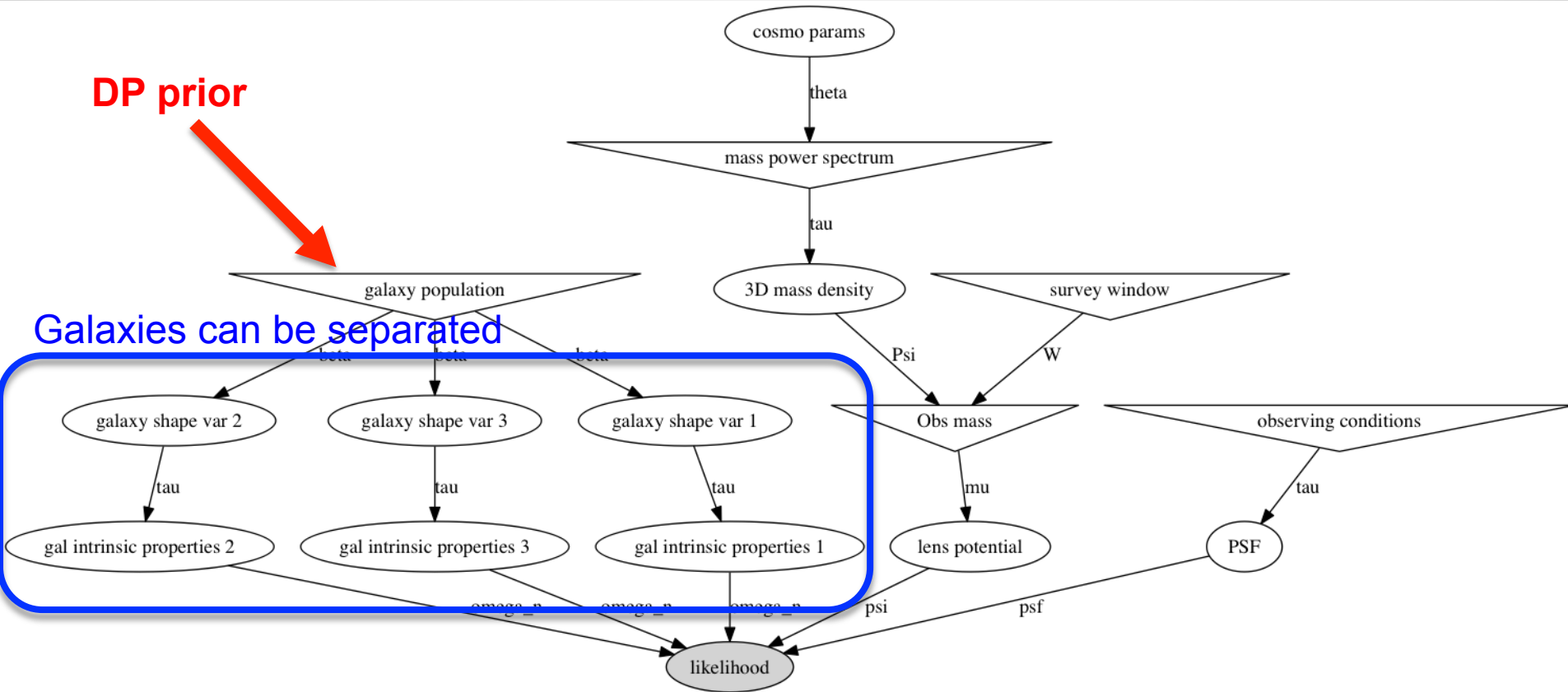
The Tractor

(D. Lang and D. Hogg)

- A generative model galaxy fitting framework
- Models PSF and galaxies as mixtures of Gaussians, to perform all convolutions analytically
- Light profiles modeled as constrained mixture of Gaussians
- Start with simple, elliptically-symmetric models
- Easy to take samples from the posterior probability distribution



Our statistical model



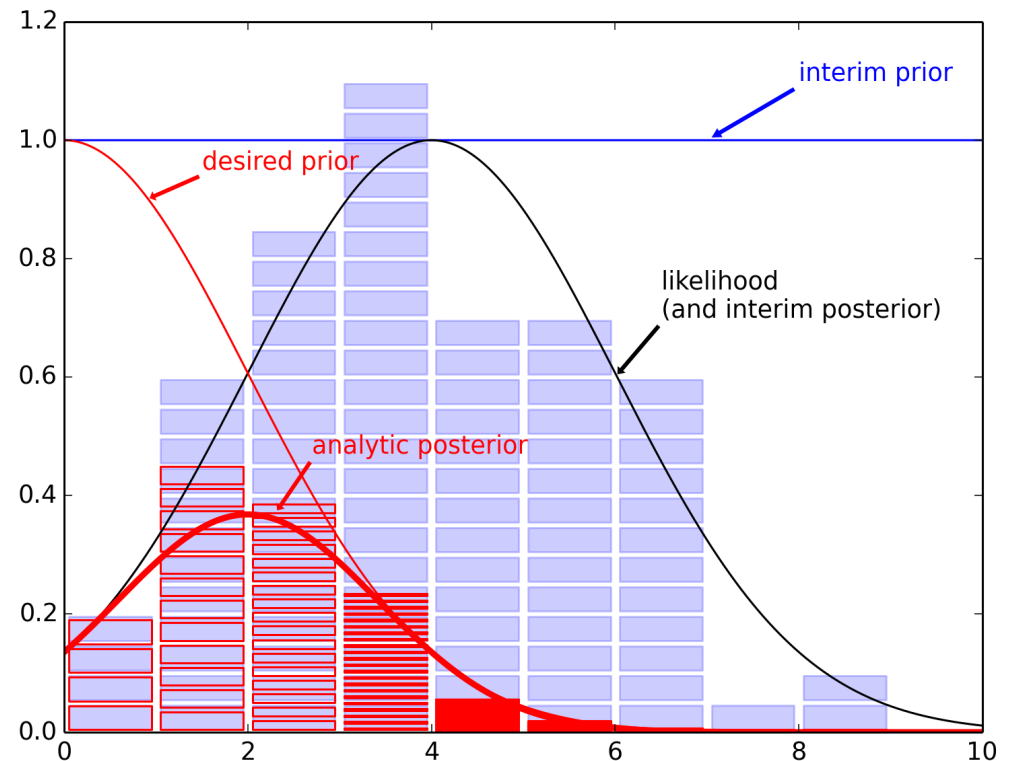
Hierarchical Inference by Importance Sampling

Use Tractor to sample galaxies individually, using interim prior.

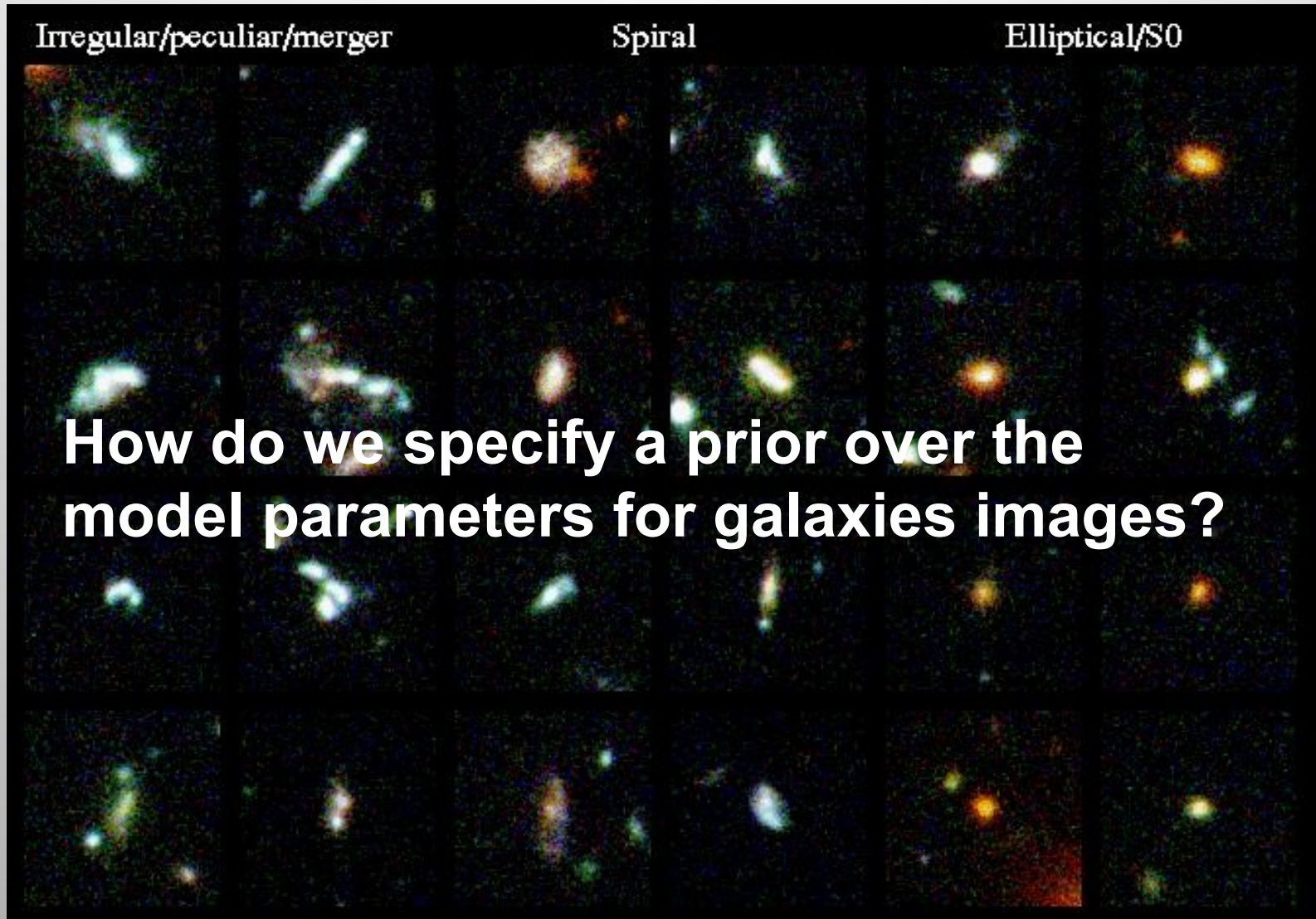
Importance sampling re-weights those samples to give desired posterior.

The inference of the independent galaxy shapes is *massively parallelizable*

Drawback is inefficiency and increased noise if interim prior is not carefully chosen.



Real galaxy images are diverse



Dirichlet Process Mixture Models

Example from Wang & Dunson (2011)

- Consider a mixture of Normal distributions,

$$y_i \sim N(\tilde{\mu}_i, \tilde{\tau}_i^{-1}), \quad (\tilde{\mu}_i, \tilde{\tau}_i^{-1}) \sim P, \quad i = 1, \dots, n, \quad P \sim DP(\kappa P_0),$$

$\alpha_i \equiv (\tilde{\mu}_i, \tilde{\tau}_i^{-1})$ parameters for galaxy i P_0 DP *base* distribution
 κ DP *precision* parameter

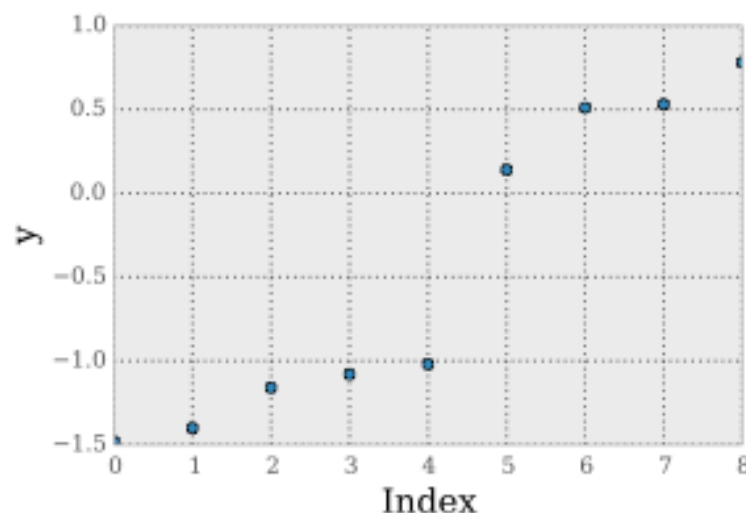
- By marginalizing over the probability measure P for each mixture we get the DP prediction rule

(Blackwell & McQueen 1973),

$$(\alpha_i | \alpha_1, \dots, \alpha_{i-1}) \sim \left(\frac{\kappa}{\kappa + i - 1} \right) P_0 + \left(\frac{1}{\kappa + i - 1} \right) \sum_{j=1}^{i-1} \delta_{\alpha_j}.$$

EXAMPLE FROM NEAL (2000)

From Neal (2000), consider a 1-D data set, y , with 9 values.

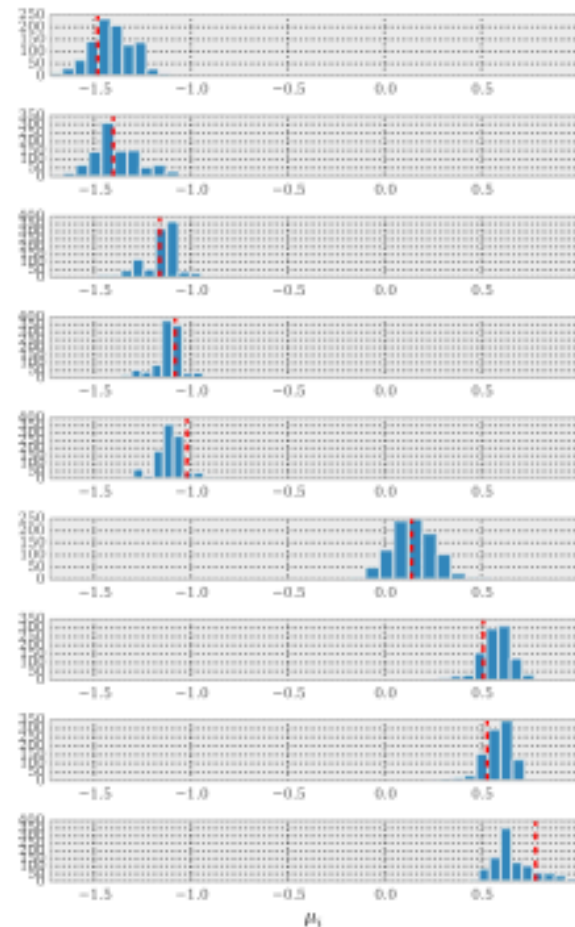


Fix the precision $\tau = 100$ and let $\alpha_i = \mu_i$ be the sampling parameter.

The DP prior is specified with a base distribution $P_0 = N(0, 1)$ and parameter $\kappa = 1$.

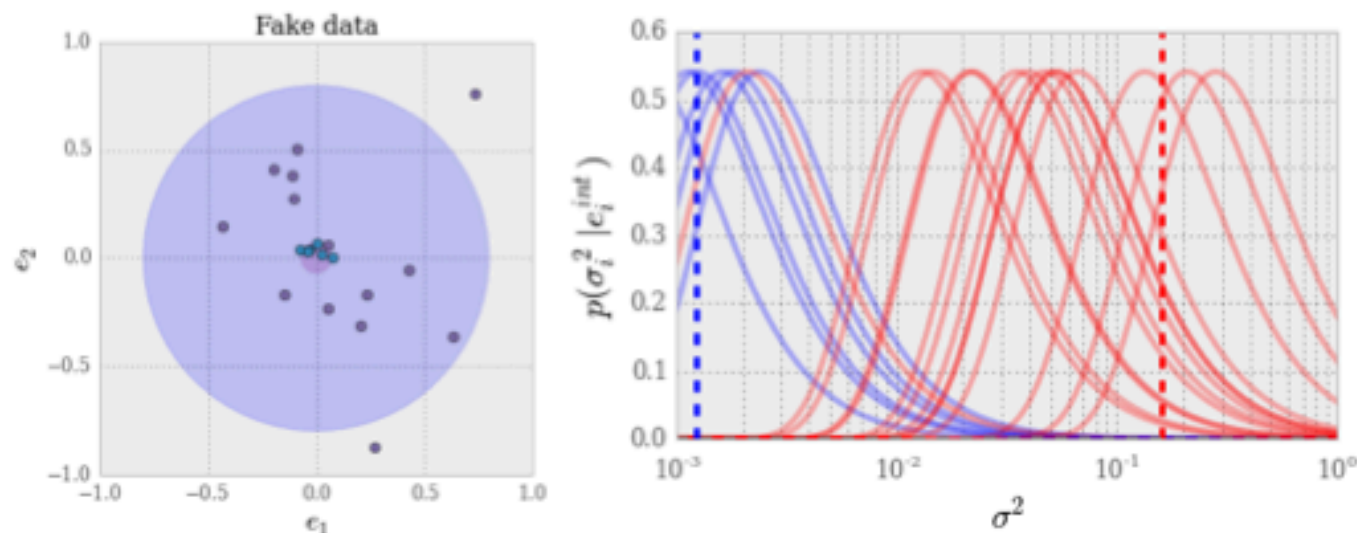
EXAMPLE FROM NEAL (2000) – POSTERIOR SAMPLES SHOW CLUSTERS

- ▶ Using conjugate Normal for the DP prior base distribution allows *Gibbs sampling*.
- ▶ Right: Histograms of posterior samples of μ_i for $i = 1, \dots, 9$.
- ▶ Red lines: y_i
- ▶ 4 clusters are found in the data – note the histogram peaks line up among clusters.



DP PRIOR FOR $\sigma_{e^{\text{int}}}^2$ (3)

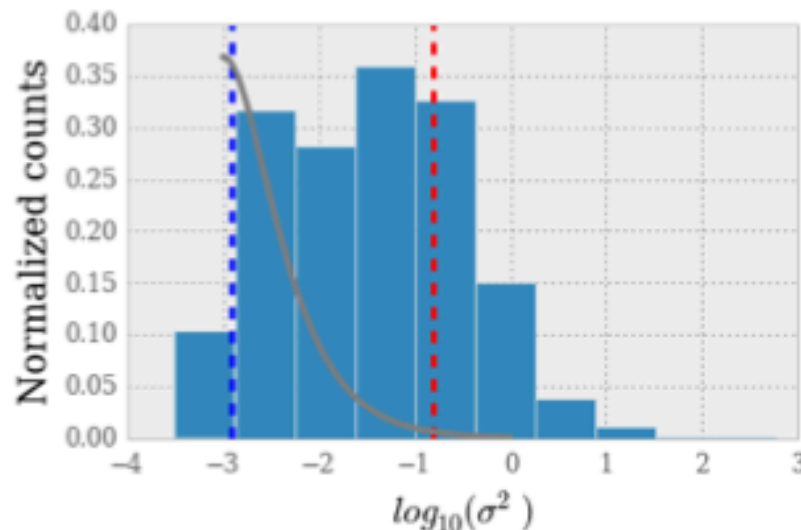
To show off the DP and to mimic the diversity in galaxy populations, generate fake data from a mixture of 2 Normal distributions with different widths (blue vs purple points in the left panel).



The right panel shows the posterior for σ_i^2 given only a single galaxy observation. Vertical lines indicate values used to generate the data. Red: galaxies from the 'wide' population, blue: galaxies from the 'narrow' population.

DP PRIOR FOR $\sigma_{e^{\text{int}}}^2$ (4)

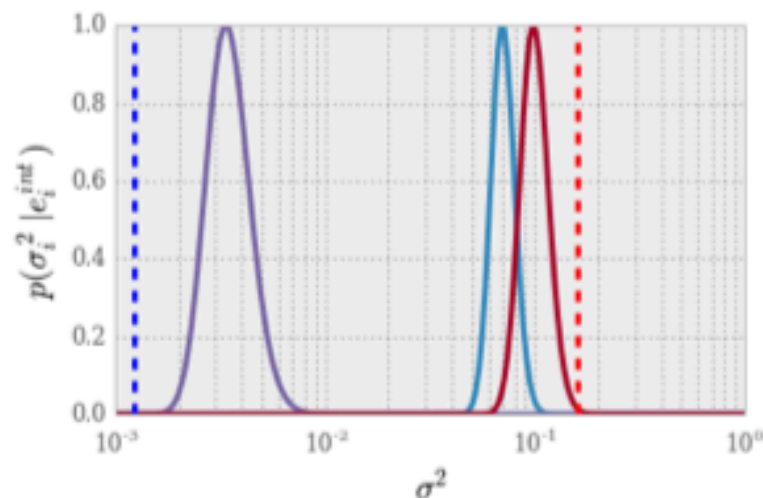
We can estimate a marginal posterior for σ^2 with a histogram of all samples for all galaxies. **Note: the 2 input values are correctly inferred.**



The red and blue vertical lines show the 2 values used to generate the data from the mixture model. The grey line shows P_0 as a conjugate inverse-Gamma distribution (not a very efficient choice).

WRONG INFERENCE: ASSUME SINGLE GAUSSIAN

- ▶ We could easily draw catastrophically wrong conclusions by assuming a less flexible prior.
- ▶ Assume the data generated from a single Normal with mean 0 and variance σ^2 .
- ▶ What posterior would we infer for σ^2 ?
 - ▶ Will be too narrow \rightarrow overconfidence in our result.
 - ▶ Sub-optimal: some data assumed to have larger variance than truth.



- ▶ Blue: all galaxies
- ▶ Red: 'broad' pop. only
- ▶ Purple: 'narrow' pop. only
- ▶ vertical lines: true σ^2 values
- ▶ All posteriors too narrow - exclude truth in all cases.

Non-conjugate priors

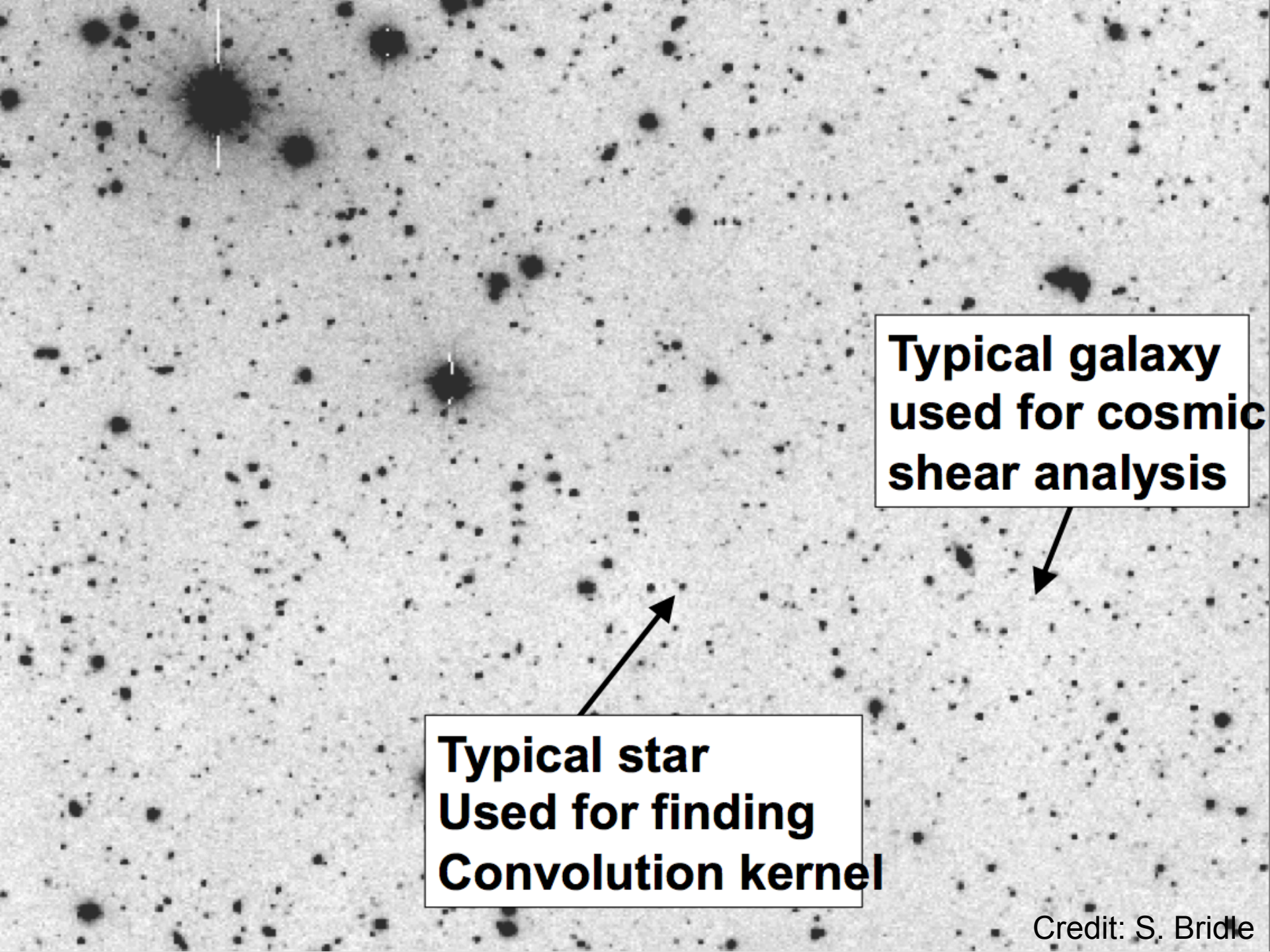
- Most DP sampling methods in the literature are limited by requirements on conjugacy.
- By importance sampling, we can use non-conjugate priors in the DP model with little additional computational complexity.

Summary: Benefits of DP prior

- Avoid overconfidence due to wrong prior specification.
- Find natural groupings of galaxy properties.
 - *Learn* how galaxies are formed – ancillary science.
- Sample based on constraints from other subsets of the data -> more efficient.

Challenges:

- The sampling model includes parameters for every galaxy.
 - Need to scale for billions of observed galaxies.
 - Parallelized Gibbs sampling?



**Typical galaxy
used for cosmic
shear analysis**

**Typical star
Used for finding
Convolution kernel**

Our statistical model

- Joint PDF factors as:

$$\begin{aligned}
 &P(D, e^{\text{obs}}, e^{\text{int}}, \sigma_e, g) \\
 &= P(D|e^{\text{obs}})P(e^{\text{obs}}|e^{\text{int}}, g)P(e^{\text{int}}|\sigma_e) \\
 &\quad P(g)P(\sigma_e)
 \end{aligned}$$

